

## Mask Set Errata for Mask 1N83J

### Introduction

This report applies to mask 1N83J for these products:

- KINETIS

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## e6990: CJTAG: possible incorrect TAP state machine advance during Check Packet

**Errata type:** Errata

**Description:** While processing a Check Packet, the IEEE 1149.7 module (CJTAG) internally gates the TCK clock to the CJTAG Test Access Port (TAP) controller in order to hold the TAP controller in the Run-Test-Idle state until the Check Packet completes. A glitch on the internally gated TCK could occur during the transition from the Preamble element to the first Body element of Check Packet processing that would cause the CJTAG TAP controller to change states instead of remaining held in Run-Test-Idle

If the CJTAG TAP controller changes states during the Check Packet due to the clock glitch, the CJTAG will lose synchronization with the external tool, preventing further communication.

**Workaround:** To prevent the possible loss of JTAG synchronization, when processing a Check Packet, provide a logic 0 value on the TMS pin during the Preamble element to avoid a possible glitch on the internally gated TCK clock.

## e6939: Core: Interrupted loads to SP can cause erroneous behavior

**Errata type:** Errata

**Description:** ARM Errata 752770: Interrupted loads to SP can cause erroneous behavior

Affects: Cortex-M4, Cortex-M4F

Fault Type: Programmer Category B

Fault Status: Present in: r0p0, r0p1 Open.

Description

If an interrupt occurs during the data-phase of a single word load to the stack-pointer (SP/R13), erroneous behavior can occur. In all cases, returning from the interrupt will result in the load instruction being executed an additional time. For all instructions performing an update to the base register, the base register will be erroneously updated on each execution, resulting in the stack-pointer being loaded from an incorrect memory location.

The affected instructions that can result in the load transaction being repeated are:

- 1) LDR SP,[Rn],#imm
- 2) LDR SP,[Rn,#imm]!
- 3) LDR SP,[Rn,#imm]
- 4) LDR SP,[Rn]
- 5) LDR SP,[Rn,Rm]

The affected instructions that can result in the stack-pointer being loaded from an incorrect memory address are:

- 1) LDR SP,[Rn],#imm
- 2) LDR SP,[Rn,#imm]!

Conditions

- 1) An LDR is executed, with SP/R13 as the destination
- 2) The address for the LDR is successfully issued to the memory system
- 3) An interrupt is taken before the data has been returned and written to the stack-pointer.

## Implications

Unless the load is being performed to Device or Strongly-Ordered memory, there should be no implications from the repetition of the load. In the unlikely event that the load is being performed to Device or Strongly-Ordered memory, the repeated read can result in the final stack-pointer value being different than had only a single load been performed.

Interruption of the two write-back forms of the instruction can result in both the base register value and final stack-pointer value being incorrect. This can result in apparent stack corruption and subsequent unintended modification of memory.

**Workaround:** Both issues may be worked around by replacing the direct load to the stack-pointer, with an intermediate load to a general-purpose register followed by a move to the stack-pointer.

If repeated reads are acceptable, then the base-update issue may be worked around by performing the stack pointer load without the base increment followed by a subsequent ADD or SUB instruction to perform the appropriate update to the base register.

## e6940: Core: VDIV or VSQRT instructions might not complete correctly when very short ISRs are used

**Errata type:** Errata

**Description:** ARM Errata 709718: VDIV or VSQRT instructions might not complete correctly when very short ISRs are used

Affects: Cortex-M4F

Fault Type: Programmer Category B

Fault Status: Present in: r0p0, r0p1 Open.

On Cortex-M4 with FPU, the VDIV and VSQRT instructions take 14 cycles to execute. When an interrupt is taken a VDIV or VSQRT instruction is not terminated, and completes its execution while the interrupt stacking occurs. If lazy context save of floating point state is enabled then the automatic stacking of the floating point context does not occur until a floating point instruction is executed inside the interrupt service routine.

Lazy context save is enabled by default. When it is enabled, the minimum time for the first instruction in the interrupt service routine to start executing is 12 cycles. In certain timing conditions, and if there is only one or two instructions inside the interrupt service routine, then the VDIV or VSQRT instruction might not write its result to the register bank or to the FPSCR.

**Workaround:** A workaround is only required if the floating point unit is present and enabled. A workaround is not required if the memory system inserts one or more wait states to every stack transaction.

There are two workarounds:

1) Disable lazy context save of floating point state by clearing LSPEN to 0 (bit 30 of the FPCCR at address 0xE000EF34).

2) Ensure that every interrupt service routine contains more than 2 instructions in addition to the exception return instruction.

## e6749: I2C: The I2C\_C1[MST] bit is not automatically cleared when arbitration is lost

**Errata type:** Errata

**Description:** When the I2C module is used as a master device and loses bus arbitration, it correctly switches to be a slave device. The I2C\_C1[MST] bit is not automatically cleared when this occurs but it does correctly operate as a slave.

**Workaround:** When the I2C module has been configured as a master device and the I2C\_S[ARB] bit is set, indicating arbitration has been lost, the I2C\_C1[MST] bit must be cleared by software before the I2C\_S[ARB] bit is cleared.

### **e3981: SDHC: ADMA fails when data length in the last descriptor is less or equal to 4 bytes**

**Errata type:** Errata

**Description:** A possible data corruption or incorrect bus transactions on the internal AHB bus, causing possible system corruption or a stall, can occur under the combination of the following conditions:

1. ADMA2 or ADMA1 type descriptor
2. TRANS descriptor with END flag
3. Data length is less than or equal to 4 bytes (the length field of the corresponding descriptor is set to 1, 2, 3, or 4) and the ADMA transfers one 32-bit word on the bus
4. Block Count Enable mode

**Workaround:** The software should avoid setting ADMA type last descriptor (TRANS descriptor with END flag) to data length less than or equal to 4 bytes. In ADMA1 mode, if needed, a last NOP descriptor can be appended to the descriptors list. In ADMA2 mode this workaround is not feasible due to ERR003983.

### **e3982: SDHC: ADMA transfer error when the block size is not a multiple of four**

**Errata type:** Errata

**Description:** Issue in eSDHC ADMA mode operation. The eSDHC read transfer is not completed when block size is not a multiple of 4 in transfer mode ADMA1 or ADMA2. The eSDHC DMA controller is stuck waiting for the IRQSTAT[TC] bit in the interrupt status register.

The following examples trigger this issue:

1. Working with an SD card while setting ADMA1 mode in the eSDHC
2. Performing partial block read
3. Writing one block of length 0x200
4. Reading two blocks of length 0x22 each. Reading from the address where the write operation is performed. Start address is 0x512 aligned. Watermark is set as one word during read. This read is performed using only one ADMA1 descriptor in which the total size of the transfer is programmed as 0x44 (2 blocks of 0x22).

**Workaround:** When the ADMA1 or ADMA2 mode is used and the block size is not a multiple of 4, the block size should be rounded to the next multiple of 4 bytes via software. In case of write, the software should add the corresponding number of bytes at each block end, before the write is initialized. In case of read, the software should remove the dummy bytes after the read is completed.

For example, if the original block length is 22 bytes, and there are several blocks to transfer, the software should set the block size to 24. The following data is written/stored in the external memory:

4 Bytes valid data  
 4 Bytes valid data  
 4 Bytes valid data  
 4 Bytes valid data  
 4 Bytes valid data  
 2 Bytes valid data + 2 Byte dummy data  
 4 Bytes valid data  
 4 Bytes valid data  
 4 Bytes valid data  
 4 Bytes valid data  
 4 Bytes valid data  
 4 Bytes valid data  
 2 Bytes valid data + 2 Byte dummy data

In this example, 48 (24 x 2) bytes are transferred instead of 44 bytes. The software should remove the dummy data.

### **e4627: SDHC: Erroneous CMD CRC error and CMD Index error may occur on sending new CMD during data transfer**

**Errata type:** Errata

**Description:** When sending new, non data CMD during data transfer between the eSDHC and EMMC card, the module may return an erroneous CMD CRC error and CMD Index error. This occurs when the CMD response has arrived at the moment the FIFO clock is stopped. The following bits after the start bit of the response are wrongly interpreted as index, generating the CRC and Index errors.

The data transfer itself is not impacted.

The rate of occurrence of the issue is very small, as there is a need for the following combination of conditions to occur at the same cycle:

- The FIFO clock is stopped due to FIFO full or FIFO empty
- The CMD response start bit is received

**Workaround:** The recommendation is to not set FIFO watermark level to a too small value in order to reduce frequency of clock pauses.

The problem is identified by receiving the CMD CRC error and CMD Index error. Once this issue occurs, one can send the same CMD again until operation is successful.

### **e3983: SDHC: Problem when ADMA2 last descriptor is LINK or NOP**

**Errata type:** Errata

**Description:** ADMA2 mode in the eSDHC is used for transfers to/from the SD card. There are three types of ADMA2 descriptors: TRANS, LINK or NOP. The eSDHC has a problem when the last descriptor (which has the End bit '1') is a LINK descriptor or a NOP descriptor.

In this case, the eSDHC completes the transfers associated with this descriptor set, whereas it does not even start the transfers associated with the new data command. For example, if a WRITE transfer operation is performed on the card using ADMA2, and the last descriptor of the WRITE descriptor set is a LINK descriptor, then the WRITE is successfully finished. Now, if a READ transfer is programmed from the SD card using ADMA2, then this transfer does not go through.

**Workaround:** Software workaround is to always program TRANS descriptor as the last descriptor.

### **e7534: SUBFAMID read back incorrect sub-family of the Kinetis device**

**Errata type:** Errata

**Description:** The current Kinetis Sub-Family ID (SUBFAMID) field of SIM\_SDID read as 0x2 if the device is K24/K64 or read as 0x1 if the device is K63. The value should be read as 0x4 for K24/K64 and 0x3 for K63.

**Workaround:** Software workaround is to read the value of RAMSIZE in System Options Register 1 (SIM\_SOPT1[RAMSIZE] = 1011b) and DIEID bits 11-7 in System Device Identification Register (SIM\_SDID[DIEID] = 00110b).

### **e7027: UART: During ISO-7816 T=0 initial character detection invalid initial characters are stored in the Rx FIFO**

**Errata type:** Errata

**Description:** When performing initial character detection (UART\_C7816[INIT] = 1) in ISO-7816 T=0 mode with UART\_C7816[ANACK] cleared, the UART samples incoming traffic looking for a valid initial character. Instead of discarding any invalid initial characters that are received, the UART will store them in the receive FIFO.

**Workaround:** After a valid initial character is detected (UART\_IS7816[INITD] sets), flush the Rx FIFO to discard any invalid initial characters that might have been received before the valid initial character.

### **e7028: UART: During ISO-7816 initial character detection the parity, framing, and noise error flags can set**

**Errata type:** Errata

**Description:** When performing initial character detection (UART\_C7816[INIT] = 1) in ISO-7816 mode the UART should not set error flags for any receive traffic before a valid initial character is detected, but the UART will still set these error flags if any of the conditions are true.

**Workaround:** After a valid initial character is detected (UART\_IS7816[INITD] sets), check the UART\_S1[NF, FE, and PF] flags. If any of them are set, then clear them.

### **e6472: UART: ETU compensation needed for ISO-7816 wait time (WT) and block wait time (BWT)**

**Errata type:** Errata

**Description:** When using the default ISO-7816 values for wait time integer (UARTx\_WP7816T0[WI]), guard time FD multiplier (UARTx\_WF7816[GTFD]), and block wait time integer (UARTx\_WP7816T1[BWI]), the calculated values for Wait Time (WT) and Block Wait Time (BWT) as defined in the Reference Manual will be 1 ETU less than the ISO-7816-3 requirement.

**Workaround:** To comply with ISO-7816 requirements, compensation for the extra 1 ETU is needed. This compensation can be achieved by using a timer, such as the low-power timer (LPTMR), to introduce a 1 ETU delay after the WT or BWT expires.

### **e4647: UART: Flow control timing issue can result in loss of characters if FIFO is not enabled**

**Errata type:** Errata

**Description:** On UART0 and UART1 when /RTS flow control signal is used in receiver request-to-send mode, the /RTS signal is negated if the number of characters in the Receive FIFO is equal to or greater than the receive watermark. The /RTS signal will not negate until after the last character (the one that makes the condition for /RTS negation true) is completely received and recognized. This creates a delay between the end of the STOP bit and the negation of the /RTS signal. In some cases this delay can be long enough that a transmitter will start transmission of another character before it has a chance to recognize the negation of the /RTS signal (the /CTS input to the transmitter).

**Workaround:** Always enable the Rx FIFO if you are using flow control for UART0 or UART1. The receive watermark should be set to seven or less. This will ensure that there is space for at least one more character in the FIFO when /RTS negates. So in this case no data would be lost.

Note that only UART0 and UART1 are affected. The UARTs that do not have the Rx FIFO feature are not affected.

### **e7029: UART: In ISO-7816 T=1 mode, CWT interrupts assert at both character and block boundaries**

**Errata type:** Errata

**Description:** When operating in ISO-7816 T=1 mode and switching from transmission to reception block, the character wait time interrupt flag (UART\_IS7816[CWT]) should not be set, only block type interrupts should be valid. However, the UART can set the CWT flag while switching from transmit to receive block and at the start of transmit blocks.

**Workaround:** If a CWT interrupt is detected at a block boundary instead of a character boundary, then the interrupt flag should be cleared and otherwise ignored.

### **e7090: UART: In ISO-7816 mode, timer interrupts flags do not clear**

**Errata type:** Errata

**Description:** In ISO-7816, when any of the timer counter expires, the corresponding interrupt status register bits gets set. The timer register bits cannot be cleared by software without additional steps, because the counter expired signal remains asserted internally. Therefore, these bits can be cleared only after forcing the counters to reload.

**Workaround:** Follow these steps to clear the UART\_IS7816 WT, CWT, or BWT bits:

1. Clear the UART\_C7816[ISO\_7816E] bit, to temporarily disable ISO-7816 mode.
2. Write 1 to the WT, CWT, or BWT bits that need to be cleared.
3. Set UART\_C7816[ISO\_7816E] to re-enable ISO-7816 mode.

Note that the timers will start counting again as soon as the ISO\_7816E bit is set. To avoid unwanted timeouts, software might need to wait until new transmit or receive traffic is expected or desired before re-enabling ISO-7816 mode.

### **e7031: UART: In single wire receive mode UART will attempt to transmit if data is written to UART\_D**

**Errata type:** Errata

**Description:** If transmit data is loaded into the UART\_D register while the UART is configured for single wire receive mode, the UART will attempt to send the data. The data will not be driven on the pin, but it will be shifted out of the FIFO and the UART\_S1[TDRE] bit will set when the character shifting is complete.

**Workaround:** Do not queue up characters to transmit while the UART is in receive mode. Always write UART\_C3[TXDIR] = 1 before writing to UART\_D in single wire mode.

### **e5704: UART: TC bit in UARTx\_S1 register is set before the last character is sent out in ISO7816 T=0 mode**

**Errata type:** Errata

**Description:** When using the UART in ISO-7816 mode, the UARTx\_S1[TC] flag sets after a NACK is received, but before guard time expires.

**Workaround:** If using the UART in ISO-7816 mode with T=0 and a guard time of 12 ETU, check the UARTn\_S1[TC] bit after each byte is transmitted. If a NACK is detected, then the transmitter should be reset.

The recommended code sequence is:

```

UART0_C2 &= ~UART_C2_TE_MASK; //make sure the transmitter is disabled at first
UART0_C3 |= UART_C3_TXDIR_MASK; //set the TX pin as output
UART0_C2 |= UART_C2_TE_MASK; //enable TX
UART0_C2 |= UART_C2_RE_MASK; //enable RX to detect NACK
for(i=0;i<length;i++)
{
while(!(UART0_S1&UART_S1_TDRE_MASK)){
UART0_D = data[i];
while(!(UART0_S1&UART_S1_TC_MASK)){//check for NACK

```



```

if(UART0_IS7816 & UART_IS7816_TXT_MASK)//check if TXT flag set
{
/* Disable transmit to clear the internal NACK detection counter */
UART0_C2 &= ~UART_C2_TE_MASK;
UART0_IS7816 = UART_IS7816_TXT_MASK;// write one to clear TXT
UART0_C2 |= UART_C2_TE_MASK; // re-enable transmit
}
}
UART0_C2 &= ~UART_C2_TE_MASK; //disable after transmit

```

### **e7091: UART: UART\_S1[NF] and UART\_S1[PE] can set erroneously while UART\_S1[FE] is set**

**Errata type:** Errata

**Description:** While the UART\_S1[FE] framing error flag is set the UART will discard any received data. Even though the data is discarded, if characters are received that include noise or parity errors, then the UART\_S1[NF] or UART\_S1[PE] bits can still set. This can lead to triggering of unwanted interrupts if the parity or noise error interrupts are enabled and framing error interrupts are disabled.

**Workaround:** If a framing error is detected (UART\_S1[FE] = 1), then the noise and parity error flags can be ignored until the FE flag is cleared. Note: the process to clear the FE bit will also clear the NF and PE bits.

### **e7092: UART: UART\_S1[TC] is not cleared by queuing a preamble or break character**

**Errata type:** Errata

**Description:** The UART\_S1[TC] flag can be cleared by first reading UART\_S1 with TC set and then performing one of the following: writing to UART\_D, queuing a preamble, or queuing a break character. If the TC flag is cleared by queuing a preamble or break character, then the flag will clear as expected the first time. When TC sets again, the flag can be cleared by any of the three clearing mechanisms without reading the UART\_S1 register first. This can cause a TC flag occurrence to be missed.

**Workaround:** If preamble and break characters are never used to clear the TC flag, then no workaround is required.

If a preamble or break character is used to clear TC, then write UART\_D immediately after queuing the preamble or break character.

### **e6933: eDMA: Possible misbehavior of a preempted channel when using continuous link mode**

**Errata type:** Errata

**Description:** When using continuous link mode ( $\text{DMA\_CR[CLM]} = 1$ ) with a high priority channel linking to itself, if the high priority channel preempts a lower priority channel on the cycle before its last read/write sequence, the counters for the preempted channel (the lower priority channel) are corrupted. When the preempted channel is restored, it runs past its "done" point instead of performing a single read/write sequence and retiring.

The preempting channel (the higher priority channel) will execute as expected.

**Workaround:** Disable continuous link mode ( $\text{DMA\_CR[CLM]}=0$ ) if a high priority channel is using minor loop channel linking to itself and preemption is enabled. The second activation of the preempting channel will experience the normal startup latency (one read/write sequence + startup) instead of the shortened latency (startup only) provided by continuous link mode.

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