

6Gbps SATA Bidirectional Redriver with Input Equalization, **Preemphasis, and Advanced Power Management**

General Description

The MAX4951C dual-channel buffer with input equalization and preemphasis is ideal to redrive internal serial-ATA (SATA) 1i, 2i, and 3i signals as well as eSATA 1m and 2m signals. The device features high electrostatic discharge (ESD) ±8kV Human Body Model (HBM) protection. The device can be placed near a SATA connector on the motherboard to overcome board losses and guarantee SATA compliance. The device is SATA specification version 3.0 (gold standard) compliant and can also be pin-configured for SATA specification version 2.6 (gold standard) compliance.

The device features hardware SATA-drive cable detection that automatically places the device into a standby mode that consumes less than 20µA (typ) standby current when no drive is connected. In addition, the device features an independent channel dynamic power-down mode where power consumption is reduced when no input signal is present. The device maintains output common-mode levels to meet internal SATA version 3.0 standards and prevent delays when coming out of low-

The device preserves signal integrity at the receiver by reestablishing full output levels and reducing the total system jitter (T_{.I}) by providing equalization. The device features channel-independent digital preemphasis controls to drive SATA outputs over longer trace lengths to meet internal SATA specifications. SATA out-of-band (OOB) signaling is supported using high-speed out-ofband signal detection on the inputs, and squelch on the corresponding outputs. Inputs and outputs are all internally 50Ω terminated and must be AC-coupled to the SATA controller IC and SATA device.

The device operates from a single +3.3V (typ) supply, is available in a small, 4mm x 4mm TQFN package with flow-through traces for ease of layout, and is specified over the commercial 0°C to +70°C operating temperature range. The MAX4951C is also pin compatible with the MAX4951BE SATA 6.0Gbps redriver.

Ordering Information appears at end of data sheet.

Benefits and Features

- **♦ Unique Design Saves Power**
 - ♦ Low-Power, 20µA (typ) SATA Cable/Drive Detect
 - ♦ Dynamic Power Reduction

Reduced Power Consumption When Idle Maintains Common-Mode Output Level No Loss of Data When Coming Out of Low-**Power Mode**

- **♦ Allows Design Flexibility**
 - ♦ Single +3.3V Supply Operation
 - ♦ SATA 3i (6.0Gbps) and SATA 2i/2m (3.0Gbps). Compliant
 - ♦ SATA 1i/1m (1.5Gbps) Compatible
- **♦ Permits Longer Trace Lengths**
 - ♦ Input Equalization
 - ♦ Selectable Output Preemphasis
- ♦ High Level of Integration for Performance
 - ♦ Excellent Input/Output Return Loss Up to 6Gbps
 - ♦ Supports SATA 2i and 3i Output Levels

 - ♦ OOB Detection: 3ns (typ)
 - ♦ High ESD Protection on All Pins: ±8kV (HBM)
- **♦** Saves Board Space
 - ♦ On-Chip 50Ω Input/Output Termination Resistors
 - ♦ Inline Signal Traces for Flow-Through Layout
 - ♦ Space-Saving, 4mm x 4mm TQFN Package with **Exposed Pad**
 - ♦ Pin Compatible with the MAX4951BE

Applications

Laptop Computers

Servers

Desktop Computers

Docking Stations

Data Storage/Workstations

For related parts and recommended products to use with this part, refer to: www.maxim-ic.com/MAX4951C.related

MIXIM

Maxim Integrated Products 1

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ABSOLUTE MAXIMUM RATINGS

(All voltages referenced to GND, unless otherwise noted.)
V _{CC} 0.3V to +4.0V
AINP, AINM, BINP, BINM, EN, CAD,
MODE, PA, PB (Note 1)0.3V to (V _{CC} + 0.3V)
Short-Circuit Output Current
BOUTP, BOUTM, AOUTP, AOUTM±30mA
Continuous Current at Inputs
AINP, AINM, BINP, BINM±5mA

Continuous Power Dissipation ($T_A = +70^{\circ}C$)	
TQFN (derate 25.6mW/°C above +70°C)	2051mW
Operating Temperature Range	0°C to +70°C
Storage Temperature Range	-55°C to +150°C
Lead Temperature (soldering, 10s)	+300°C
Soldering Temperature (reflow)	+260°C

Note 1: All I/O pins are clamped by internal diodes.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

PACKAGE THERMAL CHARACTERISTICS (Note 2)

Junction-to-Ambient Thermal Resistance (θ_{JA})........... 39°CW Junction-to-Case Thermal Resistance (θ_{JC})...... 6°C/W

Note 2: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a fourlayer board. For detailed information on package thermal considerations, refer to www.maxim-ic.com/thermal-tutorial.

ELECTRICAL CHARACTERISTICS

 $(V_{CC} = +3.0 \text{V to } +3.6 \text{V}, C_{CL} = 10 \text{nF}$ coupling capacitor on each output, $R_L = 50 \Omega$, $T_A = 0 ^{\circ} \text{C}$ to $+70 ^{\circ} \text{C}$, unless otherwise noted. Typical values are at V_{CC} = +3.3V, T_A = +25°C.) (Note 3)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Operating Power-Supply Range	V _{CC}		3.0		3.6	V
Operating Supply Current	1	PA = PB = V _{CC} , D10.2 pattern, f = 3GHz, active state		70	100	mA
Operating Supply Current	l _{cc}	PA = PB = GND, D10.2 pattern, f = 3GHz, active state		60	85	IIIA
Standby Supply Current	I _{STBY}	$EN = GND \text{ or } \overline{CAD} = V_{CC}$		20	500	μA
Dynamic Power-Down Current	I _{DYNPD}			16	20	mA
Differential Input Resistance	Z _{RX-DIFF} - DC	(Note 4)	85	100	115	Ω
Differential Output Resistance	Z _{TX-DIFF-} DC	(Note 4)	85	100	115	Ω
AC PERFORMANCE						
		150MHz ≤ f < 300MHz	18			
		300MHz ≤ f < 600MHz	14			
Differential Input Return Loss (Notes 4, 5)	RL _{RX-DIFF}	600MHz ≤ f < 1200MHz	10			dB
(110100 1, 0)		1.2GHz ≤ f < 2.4GHz	8			
		2.4GHz ≤ f ≤ 3.0GHz	3			

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ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC}=+3.0V\ to\ +3.6V,\ C_{CL}=10$ nF coupling capacitor on each output, $R_L=50\Omega$, $T_A=0$ °C to +70°C, unless otherwise noted. Typical values are at $V_{CC}=+3.3V,\ T_A=+25$ °C.) (Note 3)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
		150MHz ≤ f < 300MHz	5				
		300MHz ≤ f < 600MHz	5				
Common-Mode Input Return Loss (Notes 4, 5)	RL _{RX-CM}	600MHz ≤ f < 1200MHz	2			dB	
2000 (140100 1, 0)		1.2GHz ≤ f < 2.4GHz	2				
		$2.4GHz \le f \le 3.0GHz$	2				
		150MHz ≤ f < 300MHz	14				
D: (()) () ()		300MHz ≤ f < 600MHz	8				
Differential Output Return Loss (Notes 4, 5)	RL _{TX-DIFF}	600MHz ≤ f < 1200MHz	6			dB	
(110103 4, 0)		1.2GHz ≤ f < 2.4GHz	6				
		2.4GHz ≤ f ≤ 3.0GHz	3				
		150MHz ≤ f < 300MHz	8				
0 11 0 1 15 1		300MHz ≤ f < 600MHz	5				
Common-Mode Output Return Loss (Notes 4, 5)	RL _{TX-CM}	600MHz ≤ f < 1200MHz	2			dB	
LUSS (NOTES 4, 3)		1.2GHz ≤ f < 2.4GHz	2				
		$2.4GHz \le f \le 3.0GHz$	1				
Differential Input Cignal Dange	V _{RX-DIFF-} PP	SATA 2i, SATA 3i, MODE = GND (Note 4)	240		1000	m\/	
Differential Input Signal Range		SATA 2i, SATA 3i, MODE = V _{CC} (Note 6)	220		1000	mV _{P-P}	
Differential Output Swing	V _{TX-DIFF-} PP	f = 750MHz, f = 3.0GHz, PA = PB = GND (Notes 4, 6)	400		700	mV _{P-P}	
Output Preemphasis	V _{TX-DIFF-} PP-PE	f = 750MHz, PA = PB = V _{CC}	3		dB		
Input Equalization	V _{RX-DIFF-} PP-EQ	$V_{RX-DFF-PP} = 300 \text{mV}_{P-P}$		2.7		dB	
Preemphasis Time Period	t _{PE}	f = 750MHz, PA = PB = V _{CC}		150		ps	
Propagation Delay	t _{PD}			240		ps	
Output Rise/Fall Time	t _{TX-RISE-} FALL	PA = PB = GND, C _L = 0.5pF (Notes 5, 7)	40			ps	
Deterministic litter (Notes E. O)		Data rate = 3.0Gbps, PA = PB = GND			17		
Deterministic Jitter (Notes 5, 8)	t _{TX-DJ-DD}	Data rate = 6.0Gbps, PA = PB = GND			20	ps _{P-P}	
Random Jitter	t _{TX-RJ-DD}	PA = PB = GND (Notes 5, 8)			1.5	ps _{RMS}	
OOP Detector Threehold	\/	SATA OOB pattern, MODE = GND (Note 4)	75		200	m\/-	
OOB Detector Threshold	V _{OOB_TH}	SATA OOB pattern, MODE = V _{CC} (Note 6)	50		150	- mV _{P-P}	
OOB Output Enter/Exit Time	t _{OOB}	(Note 9)		3	5	ns	
OOB Differential Offset Delta	ΔV _{OOB} -	(Note 10)	-100		+100	mV	

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ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = +3.0 \text{V to } +3.6 \text{V}, C_{CL} = 10 \text{nF coupling capacitor on each output}, R_L = 50\Omega, T_A = 0 ^{\circ}\text{C}$ to $+70 ^{\circ}\text{C}$, unless otherwise noted. Typical values are at $V_{CC} = +3.3V$, $T_A = +25$ °C.) (Note 3)

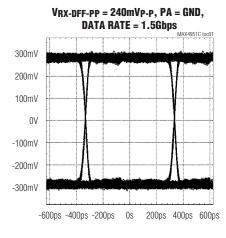
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
OOB Common-Mode Delta	ΔV _{OOB-CM}	(Note 10)	-50		+50	mV
OOB Output Disable	V _{OOB-OUT}	$V_{\text{IN}} < V_{\text{CCB}}$ (min), output voltage in squelch (Note 5)			30	mV _{P-P}
Dynamic Power-Down Exit Time	t _{DPD}	SATA OOB pattern			20	ns
Output Common-Mode Delta	ΔV _{OUT-CM}	(Note 11)	-25		+25	mV
LOGIC INPUT						
Input Logic-High	V _{IH}	EN, $\overline{\text{CAD}}$, PA, PB, MODE	1.4			V
Input Logic-Low	V _{IL}	EN, $\overline{\text{CAD}}$, PA, PB, MODE			0.6	V
Input Logic Hysteresis	V _{HYST}	EN, $\overline{\text{CAD}}$, PA, PB, MODE		0.1		V
Input Pullup/Pulldown Resistance R _{PU-PD}				370		kΩ
ESD PROTECTION						
All Pins		Human Body Model		±8		kV

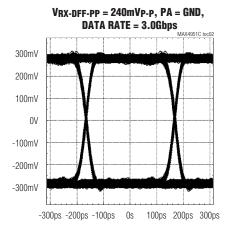
- Note 3: All devices are 100% production tested at $T_A = +70^{\circ}$ C. Specifications over the operating temperature range are guaranteed by design.
- Note 4: This specification meets SATA version 3.0 (gold standard).
- Note 5: Guaranteed by design.
- Note 6: This specification meets SATA version 2.6 (gold standard).
- Note 7: Rise and fall times are measured using 20% and 80% levels.
- Note 8: DJ measured using K28.5 pattern; RJ measured using D10.2 pattern
- Note 9: Total time for OOB detection circuit to enable/squelch the output.
- Note 10: Difference between squelched and not squelched in the active mode.
- Note 11: Difference between output common mode in the active and dynamic power-down state.

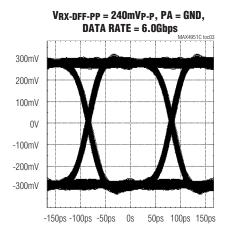
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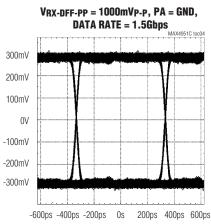
Typical Operating Characteristics

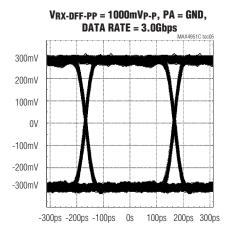
(V_{CC} = +3.3V, T_A = +25°C, all eye diagrams measured using K28.5 pattern, unless otherwise noted.)

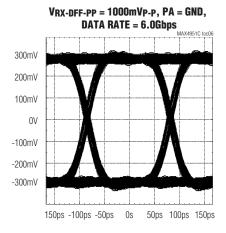


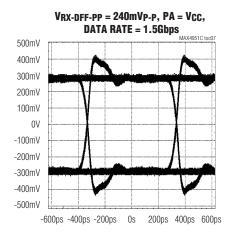


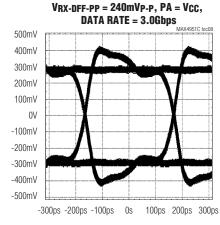


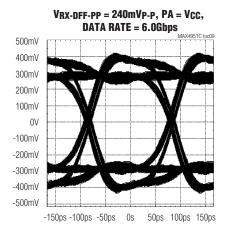








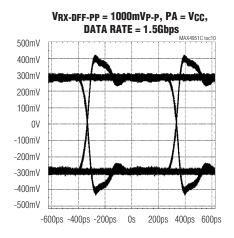


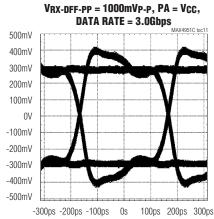


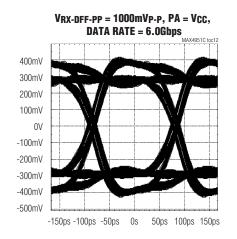
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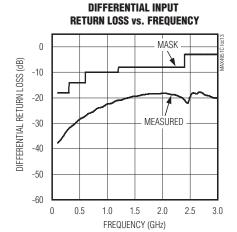
Typical Operating Characteristics (continued)

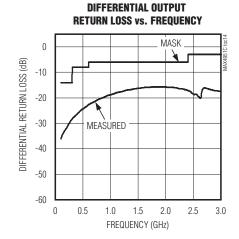
(V_{CC} = +3.3V, T_A = +25°C, all eye diagrams measured using K28.5 pattern, unless otherwise noted.)





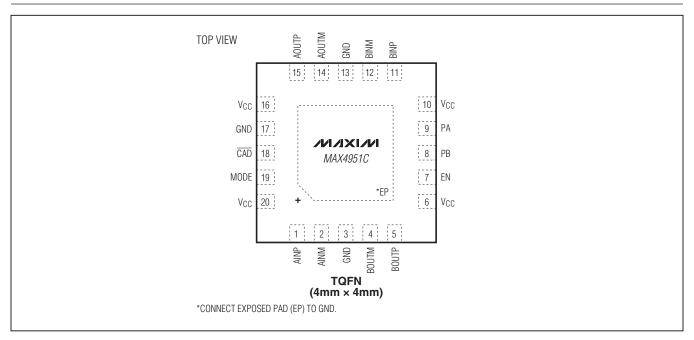






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Pin Configuration



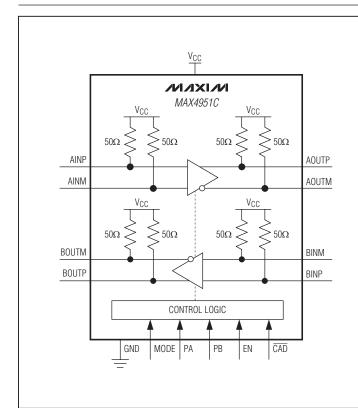
Pin Description

PIN	NAME	FUNCTION
1	AINP	Noninverting Input, Channel A
2	AINM	Inverting Input, Channel A
3, 13, 17	GND	Ground
4	BOUTM	Inverting Output, Channel B
5	BOUTP	Noninverting Output, Channel B
6, 10, 16, 20	V _{CC}	Positive Supply-Voltage Input. Bypass V_{CC} to GND with 1 μ F and 0.01 μ F capacitors in parallel as close as possible to the device.
7	EN	Active-High Enable Input. Drive EN low to put the device in standby mode. Drive EN high for normal operation. EN has a $390 \mathrm{k}\Omega$ (typ) pulldown resistor.
8	PB	Channel B Preemphasis-Enable Input. Drive PB high to enable channel B output preemphasis. Drive PB low for standard SATA output level. PB has a $390 \text{k}\Omega$ (typ) pulldown resistor.

PIN	NAME	FUNCTION
9	PA	Channel A Preemphasis-Enable Input. Drive PA high to enable channel A output preemphasis. Drive PA low for standard SATA output level. PA has a $390k\Omega$ (typ) pulldown resistor.
11	BINP	Noninverting Input, Channel B
12	BINM	Inverting Input, Channel B
14	AOUTM	Inverting Output, Channel A
15	AOUTP	Noninverting Output, Channel A
18 CAD		Active-Low Cable-Detect Input. For external SATA applications, drive $\overline{\text{CAD}}$ high to put the device in standby mode. Drive $\overline{\text{CAD}}$ low for normal operation. $\overline{\text{CAD}}$ has a 390k Ω (typ) pullup resistor. For internal SATA applications, connect $\overline{\text{CAD}}$ to ground.
19 MODE		OOB Threshold Level Set. MODE has a $390\text{k}\Omega$ (typ) pulldown resistor.
— ЕР		Exposed Pad. Internally connected to GND. EP must be electrically connected to a ground plane for proper thermal and electrical operation.

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Functional Diagram/Truth Table



MODE	V _{OOB_TH_LOW} (mV _{P-P})	V _{OOB_TH_HIGH} (mV _{P-P})
0	75	200
1	50	150

EN	PA	РВ	CHANNEL A	CHANNEL B
0	Χ	Χ	STANDBY	STANDBY
1	0	0	STANDARD SATA	STANDARD SATA
1	1	0	PREEMPHASIS	STANDARD SATA
1	0	1	STANDARD SATA	PREEMPHASIS
1	1	1	PREEMPHASIS	PREEMPHASIS

EN	CAD	STATUS		
0	0	LOW-POWER STANDBY		
0	1	LOW-POWER STANDBY		
1	0	ACTIVE		
1	1	LOW-POWER STANDBY		

NOTE: PA, PB, EN, AND MODE HAVE A $390k\Omega$ RESISTOR PULLDOWN TO GND. CAD HAS A 390kΩ RESISTOR PULLUP TO VCC. X = DON'T CARE

Detailed Description

The MAX4951C consists of two identical buffers that take SATA input signals and return them to full SATA compliant output levels. Each buffer includes an equalizer, a limiting amplifier, and an output driver with preemphasis. The buffer outputs are protected from high-voltage electrostatic discharge (ESD) to ±8kV Human Body Model (HBM).

Input/Output Terminations

Inputs and outputs are internally 50Ω terminated and must be AC-coupled to the SATA controller IC and SATA device for proper operation.

OOB Signal Detection

The device provides full OOB signal support through high-speed, OOB-detection circuitry. SATA OOB differential input signals of VOOB TH LOW or less are detected as off and are not passed to the output. This prevents the system from responding to unwanted noise. SATA OOB differential input signals of VOOB TH_HIGH or more are detected as on and passed to the output. This allows OOB signals to transmit through the device. The time for the OOB detection circuit to detect an inactive SATA OOB input and squelch the associated output, or detect an active SATA OOB input and enable the output, is 3ns (typ). The MODE pin can be used to program the OOB detection range. When MODE = GND, the SATA version 3.0 range is used. When MODE = V_{CC} , the SATA version 2.6 range is used.

Enable Input

The device features an active-high enable input (EN). EN has an internal pulldown resistor of 390k Ω (typ). Drive EN low or leave unconnected to place the device into low-power standby mode. In standby, the buffers are disabled, reducing the supply current to 20µA (typ). Drive EN high for normal operation.

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Cable-Detect Input

The device features an active-low, cable-detect input (CAD) for use in external SATA applications. CAD has an internal 390k Ω (typ) pullup resistor. Drive \overline{CAD} high or leave unconnected to place the device into low-power standby mode. In this mode, the buffers are disabled, reducing supply current to 20µA (typ). This signal is normally driven low by inserting an internal SATA cable into a properly wired socket (see the Typical Operating Circuit). If the cable-detect feature is not desired, connect CAD to GND.

Dvnamic Power-Down Mode

The device features a dynamic power-down mode where the device shuts down the major power consuming circuitry. The device detects if the input signal is not present for a 4µs (typ) duration. Normal operation resumes after 20ns (max) when a signal above the OOB threshold level is detected at the input. This function is implemented separately for both channels. The output common mode remains virtually unchanged when entering or exiting dynamic power-down mode, making the device ideal for internal SATA applications.

Output Preemphasis Selection Inputs

The device has two preemphasis control-logic inputs, PA and PB. PA and PB have internal $390k\Omega$ (typ) pulldown resistors. PA and PB enable preemphasis to the outputs of their corresponding buffers (see the Functional Diagram/Truth Table). Drive PA or PB low or leave unconnected for standard SATA output levels. Drive PA or PB high to provide preemphasis to the output. The preemphasis output signal compensates for attenuation from longer trace lengths or to meet internal SATA specifications.

Applications Information

Figure 1 shows a typical application with the device used to drive an internal SATA device. Set PB high and PA low for applications with board losses < 3dB between the MAX4951C and the connector.

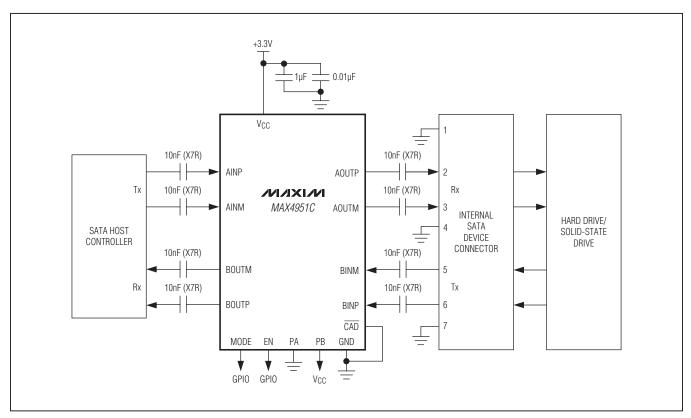


Figure 1. Typical Application Circuit for Internal SATA Applications

6Gbps SATA Bidirectional Redriver with Input Equalization, **Preemphasis, and Advanced Power Management**

Exposed-Pad Package

The exposed-pad, 20-pin TQFN package incorporates features that provide a very low-thermal resistance path for heat removal from the device. The exposed pad on the device must be soldered to GND for proper thermal and electrical performance. For more information on exposed-pad packages, refer to Application Note 862: HFAN-08.1: Thermal Considerations of QFN and Other Exposed-Paddle Packages.

Layout

Use controlled-impedance transmission lines to interface with the device's high-speed inputs and outputs. Place power-supply decoupling capacitors as close as possible to the V_{CC} pin.

Power-Supply Sequencing

Caution: Do not exceed the absolute maximum ratings because stresses beyond the listed ratings can cause permanent damage to the device.

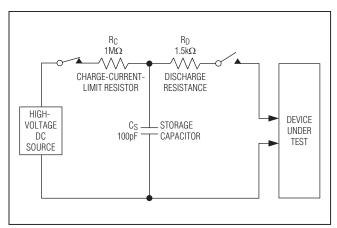


Figure 2. Human Body ESD Test Model

Proper power-supply sequencing is recommended for all devices. Always apply V_{CC} before applying signals, especially if the signal is not current limited.

ESD Protection

As with all Maxim devices, ESD protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The MAX4951C is protected against ESD events up to ±8kV (HBM). The ESD structures withstand ±8kV in all states: normal operation and powered down. After an ESD event, the device continues to function without latchup.

HBM

The device is rated for ±8kV ESD protection using the HBM (MIL-STD-883, Method 3015). Figure 2 shows the HBM voltage, and Figure 3 shows the current waveform it generates when discharged into a low-impedance state. This model consists of a 100pF capacitor charged to the ESD voltage of interest that is then discharged into the device through a $1.5k\Omega$ resistor.

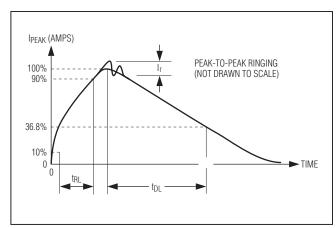
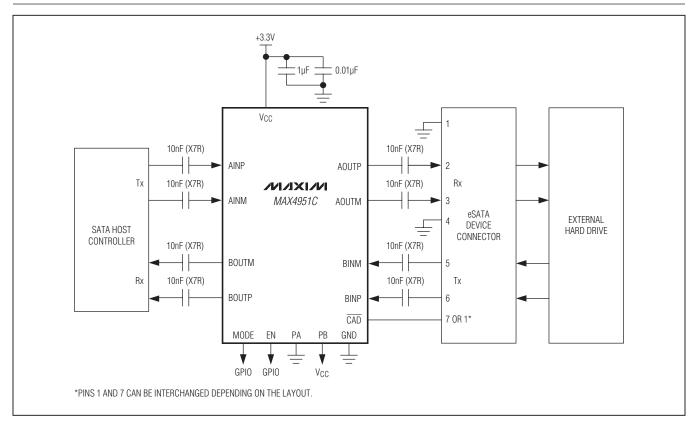


Figure 3. Human Body Current Waveform

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Typical Operating Circuit



Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX4951CCTP+	0°C to +70°C	20 TQFN-EP*

⁺Denotes a lead(Pb)-free/RoHS-compliant package.

Chip Information

PROCESS: BICMOS

Package Information

For the latest package outline information and land patterns (footprints), go to www.maxim-ic.com/packages. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAG	E PACKAG	E OUTLINE NO.	LAND
TYPE	CODE		PATTERN NO.
20 TQFN-E	EP T2044+2	2 21-0139	90-0036

^{*}EP = Exposed pad.

6Gbps SATA Bidirectional Redriver with Input Equalization, Preemphasis, and Advanced Power Management

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	3/11	Initial release	_

Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time. The parametric values (min and max limits) shown in the Electrical Characteristics table are guaranteed. Other parametric values quoted in this data sheet are provided for guidance.

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