Product data sheet Characteristics

ATV61HU22M3 SPEEDDRIVE,3HP,230V,ATV61



Main R

Main	
Range of product	Altivar 61
Product or component type	Variable speed drive
Product specific application	Pumping and ventilation machine
Component name	ATV61
Motor power kW	2.2 kW 3 phases at 200240 V 1.5 kW single phase at 200240 V
Motor power hp	3 hp 3 phases at 200240 V 2 hp single phase at 200240 V
Power supply voltage	200240 V (- 1510 %)
Supply number of phases	3 phases Single phase
Line current	18.2 A for 200 V single phase 1.5 kW / 2 hp 15.7 A for 240 V single phase 1.5 kW / 2 hp 15 A for 200 V 3 phases 2.2 kW / 3 hp 12.8 A for 240 V 3 phases 2.2 kW / 3 hp
EMC filter	Class C2 EMC filter integrated
Assembly style	With heat sink
Apparent power	5.3 kVA for 240 V 3 phases 2.2 kW / 3 hp 3.7 kVA for 240 V single phase 1.5 kW / 2 hp
Maximum prospective line Isc	5 kA single phase 5 kA 3 phases
Maximum transient current	13.2 A for 60 s 3 phases 9.6 A for 60 s single phase
Nominal switching frequency	12 kHz
Switching frequency	1216 kHz with derating factor 116 kHz adjustable
Asynchronous motor control	Voltage/Frequency ratio, 2 points Voltage/Frequency ratio, 5 points Flux vector control without sensor, standard Voltage/Frequency ratio - Energy Saving, quadratic U/f
Synchronous motor control profile	Vector control without sensor, standard
Communication port protocol	CANopen Modbus
Type of polarization	No impedance for Modbus
Option card	Profibus DP V1 communication card Profibus DP communication card Multi-pump card Modbus/Uni-Telway communication card Modbus TCP communication card Modbus Plus communication card METASYS N2 communication card LonWorks communication card Interbus-S communication card I/O extension card Fipio communication card Ethernet/IP communication card DeviceNet communication card Controller inside programmable card CC-Link communication card BACnet communication card APOGEE FLN communication card

Complementary

Asynchronous motors Synchronous motors
170264 V
5060 Hz (- 55 %)
47.563 Hz
8 A at 12 kHz, 230 V single phase 11 A at 12 kHz, 230 V 3 phases
0.11000 Hz
1100 in open-loop mode, without speed feedback
+/- 10 % of nominal slip for 0.2 Tn to Tn torque variation without speed feedback
+/- 15 % in open-loop mode, without speed feedback
130 % of nominal motor torque, +/- 10 % for 60 s
30 % without braking resistor <= 125 % with braking resistor
Frequency PI regulator
Adjustable Automatic whatever the load Can be suppressed Not available in voltage/frequency ratio (2 or 5 points)
1 LED red presence of drive voltage
<= power supply voltage
Between power and control terminals
Without mounting kit: 1-strand IEC cable at 45 °C, copper 90 °C XLPE/EPR Without mounting kit: 1-strand IEC cable at 45 °C, copper 70 °C PVC With UL Type 1 kit: 3-strand UL 508 cable at 40 °C, copper 75 °C PVC With an IP21 or an IP31 kit: 3-strand IEC cable at 40 °C, copper 70 °C PVC
L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB terminal 6 mm ² / AWG 8 AI1-/AI1+, AI2, AO1, R1A, R1B, R1C, R2A, R2B, LI1LI6, PWR terminal 2.5 mm ² / AWG 14
L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB 1.4 N.m / 12.3 lb.in Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, Ll1Ll6, PWR 0.6 N.m
Internal supply 24 V DC (2127 V), <= 200 mA for overload and short-circuit pro tection Internal supply for reference potentiometer (1 to 10 kOhm) 10.5 V DC +/- 5 %, <= 10 mA for overload and short-circuit protection External supply 24 V DC (1930 V), 30 W
2
Al2 software-configurable voltage 010 V DC, input voltage 24 V max, impedance 30000 Ohm, resolution 11 bits Al2 software-configurable current 020 mA, impedance 242 Ohm, resolution 11 bits Al1-/Al1+ bipolar differential voltage +/- 10 V DC, input voltage 24 V max, resolution 11 bits + sign
Discrete input LI6 (if configured as logic input) 2 ms, +/- 0.5 ms Discrete input LI1LI5 2 ms, +/- 0.5 ms Analog output AO1 2 ms, +/- 0.5 ms Analog input AI2 2 ms, +/- 0.5 ms Analog input AI1-/AI1+ 2 ms, +/- 0.5 ms
AO1 +/- 1 % for a temperature variation 60 °C AI2 +/- 0.6 % for a temperature variation 60 °C AI1-/AI1+ +/- 0.6 % for a temperature variation 60 °C
AO1 +/- 0.2 % AI2 +/- 0.15 % of maximum value AI1-/AI1+ +/- 0.15 % of maximum value
1
AO1 software-configurable logic output 10 V, <= 20 mA AO1 software-configurable voltage, analogue output range 010 V DC, impedance 470 Ohm, resolution 10 bits AO1 software-configurable current, analogue output range 020 mA, impedance 500 Ohm, resolution 10 bits
2
(R2A, R2B) configurable relay logic NO, electrical durability 100000 cycles (R1A, R1B, R1C) configurable relay logic NO/NC, electrical durability 100000 cycles



Maximum response time	R2A, R2B <= 7 ms, tolerance +/- 0.5 ms R1A, R1B, R1C <= 7 ms, tolerance +/- 0.5 ms <= 100 ms in STO (Safe Torque Off)
Minimum switching current	Configurable relay logic 3 mA at 24 V DC
Maximum switching current	R1, R2 on resistive load, 5 A at 30 V DC, cos phi = 1, L/R = 0 ms R1, R2 on resistive load, 5 A at 250 V AC, cos phi = 1, L/R = 0 ms R1, R2 on inductive load, 2 A at 30 V DC, cos phi = 0.4, L/R = 7 ms R1, R2 on inductive load, 2 A at 250 V AC, cos phi = 0.4, L/R = 7 ms
Discrete input number	7
Discrete input type	(PWR) safety input, 24 V DC, voltage limits <= 30 V, impedance 1500 Ohm (Ll6) switch-configurable PTC probe, 06, impedance 1500 Ohm (Ll6) switch-configurable, 24 V DC, voltage limits <= 30 V, with level 1 PLC, impedance 3500 Ohm (Ll1Ll5) programmable, 24 V DC, voltage limits <= 30 V, with level 1 PLC, impedance 3500 Ohm
Discrete input logic	LI6 (if configured as logic input) positive logic (source), < 5 V (state 0), > 11 V (state 1) LI6 (if configured as logic input) negative logic (sink), > 16 V (state 0), < 10 V (state 1) LI1LI5 positive logic (source), < 5 V (state 0), > 11 V (state 1)
Acceleration and deceleration ramps	LI1LI5 negative logic (sink), > 16 V (state 0), < 10 V (state 1) Automatic adaptation of ramp if braking capacity exceeded, by using resistor Linear adjustable separately from 0.01 to 9000 s S. U or customized
Braking to standstill	By DC injection
Protection type	Motor thermal protection Motor power removal Motor motor phase break Drive thermal protection Drive short-circuit between motor phases Drive power removal Drive overvoltages on the DC bus Drive overheating protection Drive overcurrent between output phases and earth Drive line supply undervoltage Drive line supply overvoltage Drive input phase breaks Drive break on the control circuit Drive against input phase loss Drive against exceeding limit speed
Insulation resistance	> 1 mOhm at 500 V DC for 1 minute to earth
Frequency resolution	Display unit 0.1 Hz Analog input 0.024/50 Hz
Type of connector	Male SUB-D 9 on RJ45 for CANopen 1 RJ45 for Modbus on terminal 1 RJ45 for Modbus on front face
Physical interface	2-wire RS 485 for Modbus
Transmission frame	RTU for Modbus
Transmission rate	20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen 9600 bps, 19200 bps for Modbus on front face 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal
Data format	8 bits, odd even or no configurable parity for Modbus on terminal 8 bits, 1 stop, even parity for Modbus on front face
Number of addresses	1247 for Modbus 1127 for CANopen
Method of access	Slave for CANopen
Marking	CE
Operating position	Vertical +/- 10 degree
Product weight	4 kg
Width	155 mm
Height	260 mm
Depth	187 mm



Environment

54.5 dB conforming to 86/188/EEC				
4230 V DC between control and power terminals 2830 V DC between earth and power terminals				
Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 Radiated radio-frequency electromagnetic field immunity test conforming to IEC 61000-4-3 level 3 Electrostatic discharge immunity test conforming to IEC 61000-4-2 level 3 Electrical fast transient/burst immunity test conforming to IEC 61000-4-4 level 4 Conducted radio-frequency immunity test conforming to IEC 61000-4-6 level 3				
EN 55011 class A group 1 EN 61800-3 environments 1 category C2 EN 61800-3 environments 2 category C2 EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 60721-3-3 class 3C1 IEC 60721-3-3 class 3S2 UL Type 1				
CSA C-Tick DNV GOST NOM 117 UL				
2 conforming to EN/IEC 61800-5-1				
IP54 on lower part conforming to EN/IEC 61800-5-1 IP54 on lower part conforming to EN/IEC 60529 IP41 on upper part conforming to EN/IEC 61800-5-1 IP41 on upper part conforming to EN/IEC 60529 IP21 conforming to EN/IEC 61800-5-1 IP21 conforming to EN/IEC 60529 IP20 on upper part without blanking plate on cover conforming to EN/IEC 61800-5-1 IP20 on upper part without blanking plate on cover conforming to EN/IEC 60529				
1.5 mm peak to peak (f = 313 Hz) conforming to EN/IEC 60068-2-6 1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6				
15 gn for 11 ms conforming to EN/IEC 60068-2-27				
595 % without dripping water conforming to IEC 60068-2-3 595 % without condensation conforming to IEC 60068-2-3				
5060 °C with derating factor -1050 °C without derating				
-2570 °C				

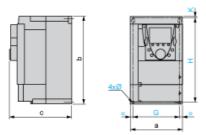


Product data sheet Dimensions Drawings

ATV61HU22M3

UL Type 1/IP 20 Drives

Dimensions without Option Card



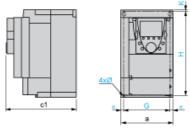
Dimensions in mm

а	b	С	G	Н	К	Ø
155	260	187	138	249	4	5

Dimensions in in.

а	b	С	G	Н	К	Ø
6.10	10.24	7.36	5.43	9.80	0.15	0.19

Dimensions with 1 Option Card (1)



Dimensions in mm

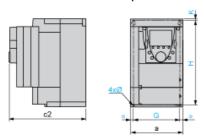
а	c1	G	Н	К	Ø
155	210	138	249	4	5

Dimensions in in.

а	c1	G	Н	К	Ø
6.10	8.26	5.43	9.80	0.15	0.19

⁽¹⁾ Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

Dimensions with 2 Option Cards (1)



Dimensions in mm

а	c2	G	Н	К	Ø
155	233	138	249	4	5

Dimensions in in.

а	c2	G	Н	К	Ø
6.10	9.17	5.43	9.80	0.15	0.19

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

Product data sheet Mounting and Clearance

ATV61HU22M3

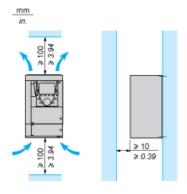
Mounting Recommendations

Depending on the conditions in which the drive is to be used, its installation will require certain precautions and the use of appropriate accessories.

Install the unit vertically:

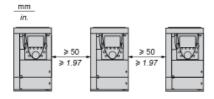
- · Avoid placing it close to heating elements
- Leave sufficient free space to ensure that the air required for cooling purposes can circulate from the bottom to the top of the unit.

Clearance

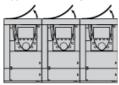


Mounting Types

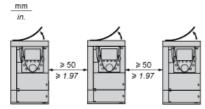
Type A Mounting



Type B Mounting



Type C Mounting



By removing the protective blanking cover from the top of the drive, the degree of protection for the drive becomes IP 20.

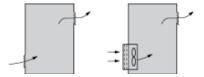
The protective blanking cover may vary according to the drive model (refer to the user guide).

Specific Recommendations for Mounting the Drive in an Enclosure

Ventilation

To ensure proper air circulation in the drive:

- · Fit ventilation grilles.
- Ensure that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must provide a flow rate at least equal to that of the drive fans (refer to the product characteristics).



- Use special filters with IP 54 protection.
- Remove the blanking cover from the top of the drive.

Dust and Damp Proof Metal Enclosure (IP 54)

The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions: dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc.

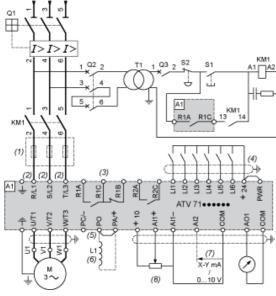
This enables the drive to be used in an enclosure where the maximum internal temperature reaches 50°C.



ATV61HU22M3

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Upstream Breaking via Contactor

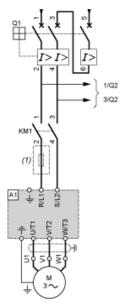


- A1 ATV61 drive
- KM1 Contactor
- L1 DC choke
- Q1 Circuit-breaker
- Q2 GV2 L rated at twice the nominal primary current of T1
- Q3 GB2CB05
- S1, XB4 B or XB5 A pushbuttons
- S2
- T1 100 VA transformer 220 V secondary
- (1) Line choke (three-phase); mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (5) There is no PO terminal on ATV61HC11Y...HC80Y drives.
- (6) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

NOTE: All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Power Section for Single-Phase Power Supply



A1 ATV61 drive

KM1 Contactor

Q1 Circuit-breaker

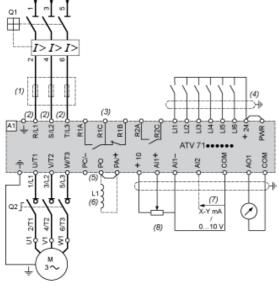
Q2 GV2 L rated at twice the nominal primary current of T1

(1) Line Choke (single-phase); mandatory for ATV61HU40M3...HU75M3 drives with a 220...240 V 50/60 Hz single-phase power supply.

NOTE: All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Downstream Breaking via Switch Disconnector



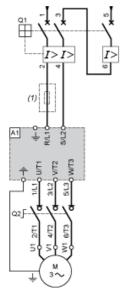
- A1 ATV61 drive
- L1 DC choke
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)
- (1) Line choke (three-phase), mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (5) There is no PO terminal on ATV61HC11Y...HC80Y drives.
- (6) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.



NOTE: All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Power Section for Single-Phase Power Supply

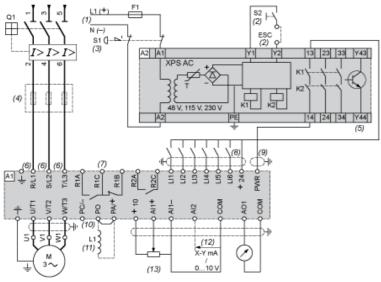


- A1 ATV61 drive
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)
- (1) Line Choke (single-phase); mandatory for ATV61HU40M3...HU75M3 drives with a 220...240 V 50/60 Hz single-phase power supply.

NOTE: All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply, Low Inertia Machine, Vertical Movement

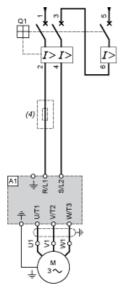


- A1 ATV61 drive
- A2 Preventa XPS AC safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" function for several drives on the same machine. In this case, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS AC module. These contacts are independent for each drive.
- F1 Fuse
- L1 DC choke
- Q1 Circuit-breaker
- S1 Emergency stop button with 2 contacts
- S2 XB4 B or XB5 A pushbutton
- (1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.
- (2) S2: resets XPS AC module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (3) Requests freewheel stopping of the movement and activates the "Power Removal" safety function.
- (4) Line choke (three-phase), mandatory for and ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).
- (5) The logic output can be used to signal that the machine is in a safe stop state.
- (6) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.
- (7) Fault relay contacts. Used for remote signalling of the drive status.
- (8) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (9) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm /0.09 in., maximum length 15 m / 49.21 ft. The cable shielding must be earthed.
- (10) There is no PO terminal on ATV61HC11Y...HC80Y drives.
- (11) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.
- (12) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (13) Reference potentiometer.

NOTE: All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1

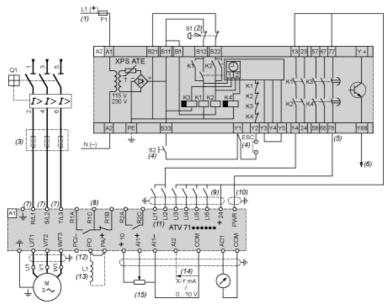
Power Section for Single-Phase Power Supply



- A1 ATV61 drive
- Q1 Circuit-breaker
- (4) Line Choke (single-phase); mandatory for ATV61HU40M3...HU75M3 drives with a 220...240 V 50/60 Hz single-phase power supply. NOTE: All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1

Three-Phase Power Supply, High Inertia Machine



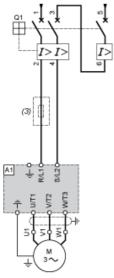
- A1 ATV61 drive
- A2 Preventa XPS ATE safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal"
- (5) safety function for several drives on the same machine. In this case the time delay must be adjusted on the drive controlling the motor that requires the longest stopping time. In addition, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS ATE module. These contacts are independent for each drive.
- F1 Fuse
- L1 DC choke
- Q1 Circuit-breaker
- S1 Emergency stop button with 2 contacts
- S2 XB4 B or XB5 A pushbutton
- (1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.
- (2) Requests controlled stopping of the movement and activates the "Power Removal" safety function.
- (3) Line choke (three-phase), mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).
- (4) S2: resets XPS ATE module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (5) The logic output can be used to signal that the machine is in a safe state.
- (6) For stopping times requiring more than 30 seconds in category 1, use a Preventa XPS AV safety module which can provide a maximum time delay of 300 seconds.
- (7) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.
- (8) Fault relay contacts. Used for remote signalling of the drive status.
- (9) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (10) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm/0.09 in., maximum length 15 m/49.21 ft. The cable shielding must be earthed.
- (11) Logic inputs LI1 and LI2 must be assigned to the direction of rotation: LI1 in the forward direction and LI2 in the reverse direction.
- (12) There is no PO terminal on ATV61HC11Y...HC80Y drives.
- (13) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.
- (14) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (15) Reference potentiometer.

NOTE: All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1



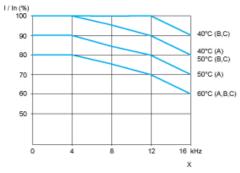
Power Section for Single-Phase Power Supply



- A1 ATV61 drive
- Q1 Circuit-breaker
- (3) Line Choke (single-phase); mandatory for ATV61HU40M3...HU75M3 drives with a 220...240 V 50/60 Hz single-phase power supply. NOTE: All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Derating Curves

The derating curves for the drive nominal current (In) depend on the temperature, the switching frequency and the mounting type (A, B or C). For intermediate temperatures (e.g. 55° C), interpolate between 2 curves.



X Switching frequency